“Linear Data Structure using Sequential Organization”

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• **Definition:**

“In computer science, **sequential** access means that a group of elements (such as **data** in a memory array or a disk file or on magnetic tape **data** storage) is accessed in a predetermined, ordered sequence. **Sequential** access is sometimes the only way of accessing the **data**, for example if it is on a tape.”
Linear Data Structure Using Sequential Organization

• Definition:

“The data structure where data items are organized sequentially or linearly one after another is called as Linear Data Structure”

A linear data structure traverses the data elements sequentially, in which only one data element can directly be reached. Ex: Arrays, Linked Lists.
Array

• **Definition:**
  ❖ “An array is a finite ordered *collection of homogeneous data elements* which provides *direct access* (or random access) to any of its elements.
  ❖ An array as a *data structure* is defined as a set of pairs (index, value) such that with each index a value is associated.

  • **index** — indicates the location of an element in an array.
  • **value** - indicates the actual value of that data element.

• Declaration of an array in ‘C++’:
  • `int Array_A[20];`

""
• **Array Representation**

• Arrays can be declared in various ways in different languages. For illustration, let's take C array declaration.

```
Index — Each location of an element in an array has a numerical index, which is used to identify the element.
```

**Array Representation**

Arrays can be declared in various ways in different languages. For illustration, let's take C array declaration.

```
int array[10] = { 35, 33, 42, 10, 14, 19, 27, 44, 26, 31 }
```

Arrays can be declared in various ways in different languages. For illustration, let's take C array declaration.

```
<table>
<thead>
<tr>
<th>elements</th>
<th>35</th>
<th>33</th>
<th>42</th>
<th>10</th>
<th>14</th>
<th>19</th>
<th>27</th>
<th>44</th>
<th>26</th>
<th>31</th>
</tr>
</thead>
<tbody>
<tr>
<td>index</td>
<td>0</td>
<td>1</td>
<td>2</td>
<td>3</td>
<td>4</td>
<td>5</td>
<td>6</td>
<td>7</td>
<td>8</td>
<td>9</td>
</tr>
</tbody>
</table>
```

Size : 10

• Arrays can be declared in various ways in different languages. For illustration, let's take C array declaration.

• As per the above illustration, following are the important points to be considered.
Array

- **Array Representation**
  - Index starts with 0.
  - Array length is 10 which means it can store 10 elements.
  - Each element can be accessed via its index. For example, we can fetch an element at index 6 as 9.

- **Basic Operations**
  - Following are the basic operations supported by an array.
  - **Traverse** – print all the array elements one by one.
  - **Insertion** – Adds an element at the given index.
  - **Deletion** – Deletes an element at the given index.
  - **Search** – Searches an element using the given index or by the value.
  - **Update** – Updates an element at the given index.
A. Memory Representation

Memory arrangement after declaring one dimensional array shown in Fig. 2.3.1.

<table>
<thead>
<tr>
<th>percentage [ 0 ]</th>
<th>3000</th>
</tr>
</thead>
<tbody>
<tr>
<td>percentage [ 1 ]</td>
<td>3004</td>
</tr>
<tr>
<td>percentage [ 2 ]</td>
<td>3008</td>
</tr>
<tr>
<td>percentage [ 3 ]</td>
<td>3012</td>
</tr>
<tr>
<td>percentage [ 4 ]</td>
<td>3016</td>
</tr>
<tr>
<td>percentage [ 5 ]</td>
<td>3020</td>
</tr>
<tr>
<td>percentage [ 6 ]</td>
<td>3024</td>
</tr>
<tr>
<td>percentage [ 7 ]</td>
<td>3028</td>
</tr>
<tr>
<td>percentage [ 8 ]</td>
<td>3032</td>
</tr>
<tr>
<td>percentage [ 9 ]</td>
<td>3036</td>
</tr>
</tbody>
</table>

Memory Address

- Initialize an array to store percentage of 10 students
  percentage[0] = 99.07;
  percentage[1] = 79.47;
  percentage[2] = 60.60;
  percentage[3] = 54.04;
  percentage[4] = 80.60;
  percentage[5] = 91.70;
  percentage[6] = 90.30;
  percentage[7] = 85.27;
  percentage[8] = 99.70;
  percentage[9] = 94.50;
ADDRESS CALCULATION

The address of the $i^{th}$ element is calculated by the following formula:

\[(\text{Base address}) + (\text{offset of the } i^{th} \text{ element from base address})\]

Here, base address is the address of the first element where array storage starts.

**Address calculation of 1D array**

Address of $arr[i] = \text{base address} + i \times \text{element\_size}$

Address of $\text{percentages}[3] = 3000 + 3 \times \text{size}\_\text{if(float)}$

\[= 3000 + 3 \times 4 = 3012\]
Abstract Data Type

• ADT is useful tool for specifying the logical properties of a data type.
• A data type is a collection of values & the set of operations on the values.
• ADT refers to the mathematical concept that defines the data type.
• ADT is not concerned with implementation but is useful in making use of data type.
ADT for an array

- Arrays are stored in consecutive set of memory locations.
- Array can be thought of as set of index and values.
- For each index which is defined there is a value associated with that index.
- There are two operations permitted on array data structure: retrieve and store.
ADT for an array

- CREATE()-produces empty array.
- RETRIVE(array,index)->value
  Takes as input array and index and either returns appropriate value or an error.
- STORE(array,index,value)-array used to enter new index value pairs.
Introduction to arrays

Representation and analysis
Type variable_name[size]

Operations with arrays:
Copy
Delete
Insert
Search
Sort
Merging of sorting arrays.
```
#include <stdio.h>

int main()
{
    int a[100], b[100] position, c n;

    printf("Enter number of elements in array\n");
    scanf("%d", &n);

    printf("Enter %d elements\n", n);
    for (c = 0; c < n; c++)
        scanf("%d", &a[c]);

    printf("Enter %d elements\n", n);
    for (c = 0; c < n - 1; c++)
        printf("%d\n", a[c]);

    //Coping the element of array a to b
    for (c = 0; c < n - 1; c++)
    {
        b[c] = a[c];
    }

    return 0;
}
```
- Enter number of elements in array - 4
- Enter 4 elements
- 1
  - 2
  - 3
  - 4
- displaying array a
  - 1
  - 2
  - 3
  - 4
- displaying array b
  - 1
  - 2
  - 3
  - 4
#include <stdio.h>

int main()
{
    int array[100], position, i, n;

    printf("Enter number of elements in array\n");
    scanf("%d", &n);

    printf("Enter %d elements\n", n);

    for (i = 0; i < n; i++)
        scanf("%d", &array[i]);

    printf("Enter the location where you wish to delete element\n");
    scanf("%d", &position);

    for (i = position; i < n; i++)
    {
        array[i] = array[i + 1];
    }

    printf("Resultant array is\n");

    for (i = 0; i < n-1; i++)
    {
        printf("%d\n", array[i]);
    }
    return 0;
}
Delete operation

```
Enter number of elements in array
5
Enter 5 elements
4
6
8
10
7
Enter the location where you wish to delete element
2
Resultant array is
4
8
10
7```
#include <stdio.h>

int main()
{
    int array[100], position, i, n, value;

    printf("Enter number of elements in array\n");
    scanf("%d", &n);

    printf("Enter %d elements\n", n);

    for (i = 0; i < n; i++)
        scanf("%d", &array[i]);

    printf("Enter the location where you wish to insert an element\n");
    scanf("%d", &position);

    printf("Enter the value to insert\n");
    scanf("%d", &value);

    for (i = n - 1; i >= position; i--)
        array[i+1] = array[i];

    array[position] = value;

    printf("Resultant array is\n");

    for (i = 0; i <= n; i++)
        printf("%d\n", array[i]);

    return 0;
}
Inserting an element

Enter number of elements in array
5
Enter 5 elements
2
5
4
3
8

Enter the location where you wish to insert an element
4
Enter the value to insert
10
Resultant array is
2
5
4
10
3
8
Int a[10]={5,4,3,2,1}
for(i=0;i<n-1;i++)
{
    for(j=0;j<=n-1;j++)
    {
        if(a[j]>a[j+1])
        {
            temp=a[i];
            a[i]=a[j];
            a[j]=temp;
        }
    }
}
#include <stdio.h>

int main() {
    int array[100], n, i, temp, end;

    scanf("%d", &n);
    end = n - 1;

    for (i = 0; i < n; i++) {
        scanf("%d", &array[i]);
    }

    for (i= 0; < n/2; i++)
    {
        temp = array[i];
        array[i] = array[end];
        array[end] = temp;

        end--;
    }

    printf("Reversed array elements are: \n");

    for ( i= 0; i < n; i++) {
        printf("%d\n", array[i]);
    }

    return 0;
}
Sort element using array

int a[10] = {5, 4, 3, 2, 1}
for (i = 0; i < n; i++)
    for (j = i + 1; j < n; j++)
    {
        if (a[i] > a[j])
        {
            temp = a[i];
            a[i] = a[j];
            a[j] = temp;
        }
    }
Two-dimensional Arrays in C

- multidimensional array is the two-dimensional array
- type arrayName [ x ][ y ];
Two-dimensional Arrays in C

<table>
<thead>
<tr>
<th></th>
<th>Column 0</th>
<th>Column 1</th>
<th>Column 2</th>
<th>Column 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Row 0</td>
<td>a[0][0]</td>
<td>a[0][1]</td>
<td>a[0][2]</td>
<td>a[0][3]</td>
</tr>
<tr>
<td>Row 1</td>
<td>a[1][0]</td>
<td>a[1][1]</td>
<td>a[1][2]</td>
<td>a[1][3]</td>
</tr>
</tbody>
</table>
m-no of rows
n-no of columns
Printf(“\n Enter the rows and columns”);
Scanf(%d %d”,&m,&n);
for(i=0;i<m;i++)
{
    for(j=0;j<n;j++)
    {
        printf(“\n Enter the value of(%d)(%d)=" ,i,j);
        scanf(“%d”,&a[i][j]);
    }
}

for(i=0;i<m;i++)
{
    printf("\n");
    for(j=0;j<n;j++)
    {
        printf("%d",&a[i][j]);
    }
}


Formally ADT is a collection of domain, operations, and axioms (or rules)

For defining an array as an ADT, we have to define its very basic operations or functions that can be performed on it

The basic operations of arrays are creation of an array, storing an element, accessing an element, and traversing the array
List of operation on Array :-

1. Inserting an element into an array
2. Deleting element from array
3. Searching an element from array
4. Sorting the array element
N -dimensional Arrays

1D (One Dimension):

Let $A[m_1]$ be a one-dimensional array. Let $A[0]$ be stored at address $Base = X$. Now assuming one element per location, the address of $A[1]$ is $X+1$, address of an arbitrary element $A[i]$ is given by $X + i$, and the address of $A[m_1-1]$ is $X + m_1 - 1$.

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>X</td>
<td>X+1</td>
<td>X+2</td>
<td>..........</td>
<td>X+i</td>
<td>..........</td>
<td>X + (m_1 - 1)</td>
</tr>
</tbody>
</table>
2D (Two Dimension):

Now consider two-dimensional array $A[m_1][m_2]$ which has $m_1$ rows as row$_1$, row$_2$ \ldots row$_{m_1{-}1}$ and each row contains $m_2$ elements as there are $m_2$ columns.

\[
\begin{array}{c|ccccc}
 & \text{col 1} & \text{col 2} & \cdots & \text{col } m_2 \\
\hline
\text{row 1} & - & - & & - \\
\text{row 2} & - & - & & - \\
\hline
\end{array}
\]

$A_{ij}$
Now let $A[0][0]$ be stored at address $X$ then $A[0][1]$ would be stored at $X+1$; $A[0][i]$ would be at $X+i$ and so on till $A[0][m_2-1]$ at $X + (m_2-1)$. Now address of $A[i][0]$ would be $X + (i \cdot m_2)$. Address of $A[i][j]$ is $X + (i \cdot m_2) + j$.

Row-Major representation of 2D array
Three dimensions row-major arrangement
The address of $A[i][j][k]$ is computed as

$$\text{Addr of } A[i][j][k] = X + i \cdot m_2 \cdot m_3 + j \cdot m_3 + k$$

By generalizing this we get the address of $A[i_1][i_2][i_3]$ ... [ in] in n-dimensional array $A[m_1][m_2][m_3]$ ....[ mn ]

Consider the address of $A [o][o][o]$.....[o] is $X$ then the address of $A [i][o][o]$.....[o] = $X + (i_1 \cdot m_2 \cdot m_3 \cdot - - - \cdot mn )$ and

Address of $A [i_1][i_2]$ .... [o] = $X + (i_1 \cdot m_2 \cdot m_3 \cdot - - - \cdot mn ) + (i_2 \cdot m_3 \cdot m_4 \cdot - - - \cdot mn)$

Continuing in a similar way, address of $A[i_1][i_2][i_3]$- - -[ in] will be

Address of $A[i_1][i_2][i_3]$----[ in] = $X + (i_1 \cdot m_2 \cdot m_3 \cdot - - - \cdot mn ) + (i_2 \cdot m_3 \cdot m_4 \cdot - - - \cdot mn ) + (i_3 \cdot m_4 \cdot m_5\cdot - - \cdot mn ) + (i_4 \cdot m_5 \cdot m_6\cdot - - \cdot mn ) + \ldots \ldots + in = x + \sum_{j=1}^{n} i_j \cdot A_j$
```c
#include <stdio.h>

int main ()
{
    int a[10], i, size;

    printf("\nhow many no of elements u want to scan");
    scanf("%d", &size);

    printf("\nEnter the elements in the array");
    for(i = 0; i < size; i++)
    {
        scanf("%d", &a[i]);
    }

    for(i = 0; i < size; i++)
    {
        printf("The array is %d", a[i]); //Displaying Array
    }

    return 0;
}
```
Output will be
Multi-dimensional Arrays in C

- type name[size1][size2]...[sizeN];
Two-dimensional Arrays in C

- multidimensional array is the two-dimensional array

- type arrayName [ x ][ y ];
Two-dimensional Arrays in C

<table>
<thead>
<tr>
<th></th>
<th>Column 0</th>
<th>Column 1</th>
<th>Column 2</th>
<th>Column 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Row 0</td>
<td>a[0][0]</td>
<td>a[0][1]</td>
<td>a[0][2]</td>
<td>a[0][3]</td>
</tr>
<tr>
<td>Row 1</td>
<td>a[1][0]</td>
<td>a[1][1]</td>
<td>a[1][2]</td>
<td>a[1][3]</td>
</tr>
</tbody>
</table>
• Initializing Two-Dimensional Arrays

```c
int a[3][4] = { {0, 1, 2, 3} , /* initializers for row indexed by 1 */
                 {4, 5, 6, 7} ,
                 {8, 9, 10, 11} /* initializers for row indexed by 2 */ };```

H O W T O I N I T I A L I Z E 2 - D A R R A Y I N P R O G R A M
Accessing Two-Dimensional Array Elements

```
int val = a[2][3];
```
Three-dimensional Arrays in C

- For example, the following declaration creates a three-dimensional integer array –

- Ex-int threedim[5][10][4];
Arrays support various operations such as traversal, sorting, searching, insertion, deletion, merging, block movement, etc.

Insertion of an element into an array
Deleting an element
Memory Representation of Two-Dimensional Arrays
### Row-major Representation

### Column-major Representation

<table>
<thead>
<tr>
<th>Rows</th>
<th>[ R ]</th>
<th>[ R_i ]</th>
<th>Columns</th>
</tr>
</thead>
<tbody>
<tr>
<td>[ A_{11} ] [ A_{12} ] [ \ldots ] [ A_{1n} ]</td>
<td>[ A_{m1} ] [ A_{m2} ] [ \ldots ] [ A_{mn} ]</td>
<td>[ Col_1 ] [ col_2 ] [ \ldots ] [ col_n ]</td>
<td></td>
</tr>
</tbody>
</table>

Matrix \( M = \)

\[
\begin{bmatrix}
1 & 2 & 3 & 4 \\
5 & 6 & 7 & 8 \\
9 & 10 & 11 & 12
\end{bmatrix}
\]
Row-major representation

Address Calculation of 2D array

A. Row major representation

Address of [i][j] = base address + i * c * element_size $+ j \times$ element_size

$= \text{base address} + (i \times c + j) \times \text{element_size}$

Example

For this array the row-major representation will be:

```
  0  1  2  3
0  8  6  5  4
1  2  1  9  7
2  3  6  4  2
```

Example

- Adresss of arr[1][2] (Consider base address as 1000)

  \[
  \text{Arr}[1][2] = 1000 + (1 \times 3 + 2) \times \text{sizeof(int)}
  \]

  \[
  = 1000 + 10 = 1010
  \]

B. Column major representation

Address of [i][j] = base address + j * r * element_size

$+ i \times \text{element_size}$

$= \text{base address} + (j \times r + i) \times \text{element_size}$

Example

For column-major order, all elements of the first column come before all elements of the second column, etc.

Example

- Address of arr[1][2] (Consider base address as 1000)

  \[
  \text{Arr}[1][2] = 1000 + (2 \times 4 + 1) \times \text{sizeof(int)}
  \]

  \[
  = 1000 + 18 = 1018
  \]
In row-major representation, the elements of Matrix are stored row-wise, i.e., elements of 1st row, 2nd row, 3rd row, and so on till $m^{th}$ row.
Row major arrangement

Row-major arrangement in memory, in row major representation
The address of the element of the $i^{th}$ row and the $j^{th}$ column for matrix of size $m \times n$ can be calculated as:

$$\text{Addr}(A[i][j]) = \text{Base Address} + \text{Offset} = \text{Base Address} + (\text{number of rows placed before } i^{th} \text{ row} \times \text{size of row}) \times (\text{Size of Element}) + (\text{number of elements placed before in } j^{th} \text{ element in } i^{th} \text{ row}) \times \text{size of element}$$

As row indexing starts from $0$, $i$ indicate number of rows before the $i^{th}$ row here and similarly for $j$.

For Element Size = 1 the address is

$$\text{Address of } A[i][j] = \text{Base} + (i \times n) + j$$
In general,

\[ \text{Addr}[i][j] = ((i-LB_1) \times (UB_2 - LB_2 + 1) \times \text{size}) + ((j-LB_2) \times \text{size}) \]

where number of rows placed before ith row = (i – LB1)

where LB1 is the lower bound of the first dimension.

Size of row = (number of elements in row) \times (size of element)

Memory Locations

The number of elements in a row = (UB_2 – LB_2 + 1)

where UB2 and LB2 are upper and lower bounds of the second dimension.
Column-major representation

- In column-major representation, $m \times n$ elements of a two-dimensional array $A$ are stored as one single row of columns.
- The elements are stored in the memory as a sequence as first the elements of column 1, then elements of column 2 and so on till elements of column $n$. 
Column-major arrangement

Column-major arrangement in memory, in column major representation
The address of $A[i][j]$ is computed as:

$$\text{Addr}(A[i][j]) = \text{Base Address} + \text{Offset} = \text{Base Address} + (\text{number of columns placed before } j\text{th column} \times \text{size of column}) \times (\text{Size of Element}) + (\text{number of elements placed before in } i\text{th element in } i\text{th row}) \times \text{size of element}$$

For $\text{Element\_Size} = 1$ the address is:

$$\text{Address of } A[i][j] \text{ for column major arrangement} = \text{Base} + (j \times m) + I$$

In general, for column-major arrangement; address of the element of the $j$th row and the $j$th column therefore is:

$$\text{Addr} \ (A[i][j]) = ((j - LB2) \times (UB1 - LB1 + 1) \times \text{size}) + ((i - LB1) \times \text{size})$$
Example 2.1: Consider an integer array, int A[3][4] in C++. If the base address is 1050, find the address of the element A[2][3] with row-major and column-major representation of the array.

For C++, lower bound of index is 0 and we have m=3, n=4, and Base= 1050. Let us compute address of element A[2][3] using the address computation formula

1. **Row-Major Representation:**

   Address of A[2][3] = Base + (i * n) + j
   
   = 1050 + (2 * 4) + 3
   
   = 1061
<table>
<thead>
<tr>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
<th>9</th>
<th>10</th>
<th>11</th>
<th>12</th>
</tr>
</thead>
<tbody>
<tr>
<td>(0,0)</td>
<td>(0,1)</td>
<td>(0,2)</td>
<td>(0,3)</td>
<td>(1,0)</td>
<td>(1,1)</td>
<td>(1,2)</td>
<td>(1,3)</td>
<td>(2,0)</td>
<td>(2,1)</td>
<td>(2,2)</td>
<td>(2,3)</td>
</tr>
<tr>
<td>Row1</td>
<td>Row2</td>
<td>Row3</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Row-Major Representation of 2-D array
2. Column-Major Representation:

Address of $A_{2}[3] = \text{Base} + (j \times m) + i$

\[
= 1050 + (3 \times 3) + 2 \\
= 1050 + 11 \\
= 1061
\]

- Here the address of the element is same because it is the last member of last row and last column.
<table>
<thead>
<tr>
<th>Col 1</th>
<th>Col 2</th>
<th>Col 3</th>
<th>Col 4</th>
</tr>
</thead>
<tbody>
<tr>
<td>(0,0)</td>
<td>(1,0)</td>
<td>(2,0)</td>
<td>(0,1)</td>
</tr>
<tr>
<td>(1,1)</td>
<td>(2,1)</td>
<td>(0,2)</td>
<td>(1,2)</td>
</tr>
<tr>
<td>(2,2)</td>
<td>(0,3)</td>
<td>(1,3)</td>
<td>(2,3)</td>
</tr>
</tbody>
</table>

Column-Major Representation of 2-D array
Characteristics of array

- An array is a finite ordered collection of homogeneous data elements.
- In array, successive elements of list are stored at a fixed distance apart.
- Array is defined as set of pairs-( index and value).
- Array allows random access to any element.
- In array, insertion and deletion of element in between positions requires data movement.
- Array provides static allocation, which means space allocation done once during compile time, can not be changed run time.
Advantage of Array Data Structure

- Arrays permit efficient random access in constant time $o(1)$.
- Arrays are most appropriate for storing a fixed amount of data and also for high frequency of data retrievals as data can be accessed directly.
- Wherever there is a direct mapping between the elements and there positions, arrays are the most suitable data structures.
- Ordered lists such as polynomials are most efficiently handled using arrays.
- Arrays are useful to form the basis for several more complex data structures, such as heaps, and hash tables and can be used to represent strings, stacks and queues.
Disadvantage of Array Data Structure

- Arrays provide static memory management. Hence during execution the size can neither be grown nor shrunk.
- Array is inefficient when often data is to inserted or deleted as inserting and deleting an element in array needs a lot of data movement.
- Hence array is inefficient for the applications, which very often need insert and delete operations in between.
Applications of Arrays

Although useful in their own right, arrays also form the basis for several more complex data structures, such as heaps, hash tables and can be used to represent strings, stacks and queues.

All these applications benefit from the compactness and direct access benefits of arrays.

Two-dimensional data when represented as Matrix and matrix operations.
CONCEPT OF ORDERED LIST

- Ordered list is the most common and frequently used data object
- Linear elements of an ordered list are related with each other in a particular order or sequence
- Following are some examples of the ordered list.

- 1, 3, 5, 7, 9, 11, 13, 15
- January, February, March, April, May, June, July, August, September,
- October, November, December
- Red, Blue, Green, Black, Yellow
There are many basic operations that can be performed on the ordered list as follows:

- Finding the length of the list
- Traverse the list from left to right or from right to left
- Access the ith element in the list
- Update (Overwrite) the value of the ith position
- Insert an element at the ith location
- Delete an element at the ith position
A polynomial $p(x)$ is the expression in variable $x$ which is in the form $(ax^n + bx^{n-1} + \ldots + jx + k)$, where $a, b, c \ldots, k$ fall in the category of real numbers and 'n' is non-negative integer, which is called the degree of polynomial.

An important characteristic of polynomial is that each term in the polynomial expression consists of two parts:

- One is the coefficient
- Other is the exponent

Example

$10x^2 + 26x$, here 10 and 26 are coefficients and 2, 1 are its exponential value.

A polynomial of a single variable $A(x)$ can be written as

$$a_nx^n + a_{n-1}x^{n-1} + a_{n-2}x^{n-2} + \ldots \ldots a_1x + a_0$$

where $a_n \neq 0$ and degree of $A(x)$ is $n$. 
Single Variable Polynomial

- Representation Using Arrays
- Array of Structures
- Polynomial Evaluation
- Polynomial Addition
- Multiplication of Two Polynomials
Polynomial Representation on array

- It is possible to maintain polynomials such as $5x^4 - 10x^3 + 3x^2 + 10x - 1$ using array. On polynomial some basic operations such as addition and multiplication are often implemented. In such case there is need to represent polynomials.

- The easiest method of representing a polynomial having degree $n$ is storing the coefficient of $(n + 1)$ terms of the polynomial in the respective array.

- For this purpose each and every array element must have two values; coefficient and exponent.

- In this representation, it is considered that the exponent of each successive term is less than its previous term.
Polynomial Representation

- Array representation of polynomial assumes that the exponents of the given expression are arranged from 0 to the highest value (degree), which is represented by the subscript of the array beginning with 0.
- The coefficients of the respective exponent are placed at an appropriate index in the array.

For example

\[ Q(x) = 5x^4 - 10x^3 + 3x^2 + 10x - 1. \]

\[
\begin{array}{|c|c|}
\hline
\text{Exponent} & \text{Coefficient} \\
\hline
0 & -1 \\
1 & 10 \\
2 & 3 \\
3 & -10 \\
4 & 5 \\
5 & \\
6 & \\
\hline
\end{array}
\]

Fig. 2.8.1: Polynomial Representation using Array
Polynomial as an ADT, the basic operations are as follows:

- Creation of a polynomial
- Addition of two polynomials
- Subtraction of two polynomials
- Multiplication of two polynomials
- Polynomial evaluation
Polynomial by using Array

### POLYNOMIAL of degree 3 \( P(x) = 3x^3 + x^2 - 2x + 5 \)

<table>
<thead>
<tr>
<th>INDEX ( i )</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>.....</th>
<th>N-1</th>
</tr>
</thead>
<tbody>
<tr>
<td>COEF</td>
<td>3</td>
<td>1</td>
<td>-2</td>
<td>0</td>
<td>.....</td>
<td>0</td>
</tr>
</tbody>
</table>

### POLYNOMIAL of degree 8 \( P(x) = 11x^8 + 5x^6 + x^5 + 2x^4 - 3x^2 + x + 10 \)

<table>
<thead>
<tr>
<th>INDEX ( i )</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>COEF</td>
<td>11</td>
<td>0</td>
<td>5</td>
<td>1</td>
<td>2</td>
<td>0</td>
<td>-3</td>
<td>1</td>
<td>10</td>
</tr>
</tbody>
</table>
Polynomial by using Array

POLYNOMIAL of degree 99 $P(x) = x^{99} + 78$

<table>
<thead>
<tr>
<th>INDEX $i$</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>.....</th>
<th>99</th>
</tr>
</thead>
<tbody>
<tr>
<td>COEF</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>.....</td>
<td>78</td>
</tr>
</tbody>
</table>
Structure is better than array for Polynomial:

- Such representation by an array is both time and space efficient when polynomial is not a sparse one such as polynomial $P(x)$ of degree 3 where $P(x) = 3x^3 + x^2 - 2x + 5$.
- But when polynomial is sparse such as in worst case a polynomial as $A(x) = x^{99} + 78$ for degree of $n = 100$, then only two locations out of 101 would be used.
- In such cases it is better to store polynomial as pairs of coefficient and exponent. We may go for two different arrays for each or a structure having two members as two arrays for each of coeff. and Exp or an array of structure that consists of two data members coefficient and exponent.
Polynomial by using structure

Let us go for structure having two data members coefficient and exponent and its array.
SPARSE MATRIX

- In many situations, matrix size is very large but out of it, most of the elements are zeros (not necessarily always zeros).

- And only a small fraction of the matrix is actually used. A matrix of such type is called a sparse matrix,

2.9.1 Sparse Matrix Representation

Array Representation of Sparse Matrix

- 2D array is used to represent a sparse matrix in which there are three rows named as

- Row : Index of row, where non-zero element is located,

- Column : Index of column, where non-zero element is located
Value: Value of the non zero element located at index – (row, column)

Fig. 2.9.1: Sparse Matrix
Let us take an example of a logical matrix $LA$ and $LB$ as follows:

$$LA = \begin{pmatrix}
0 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 \\
0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 \\
0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0
\end{pmatrix}_{7 \times 5}$$

$$LB = \begin{pmatrix}
0 & 1 & 1 & 1 & 1 \\
1 & 1 & 1 & 1 & 0 \\
1 & 0 & 1 & 1 & 1 \\
1 & 1 & 1 & 0 & 1 \\
1 & 1 & 1 & 1 & 1 \\
1 & 1 & 1 & 0 & 1 \\
1 & 0 & 1 & 1 & 1
\end{pmatrix}_{7 \times 5}$$

**Sparse Logical Matrix**
Sparse matrix and its representation
Transpose Of Sparse Matrix

- Simple Transpose
- Fast Transpose
To transpose a matrix, we must interchange the rows and columns. This means that if an element is at position \([j][k]\) in the original matrix, then it is at position \([k][j]\) in the transposed matrix.

When \(k = j\), the elements on the diagonal will remain unchanged. Since the original matrix is organized by rows, our first idea for a transpose algorithm might be the following:

```
for (each row k)
take element \((k,j, value)\) and
store it in \((j,k, value)\) of the transpose;
```

**For example**

**Sp1**

<table>
<thead>
<tr>
<th>Index</th>
<th>Row</th>
<th>Column</th>
<th>value</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>3</td>
<td>4</td>
<td>4</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0</td>
<td>5</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>3</td>
<td>2</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>4</td>
<td>2</td>
<td>3</td>
<td>2</td>
</tr>
</tbody>
</table>

**Sp2**

<table>
<thead>
<tr>
<th>Index</th>
<th>Row</th>
<th>Column</th>
<th>value</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>4</td>
<td>3</td>
<td>4</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
<td>5</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>2</td>
<td>1</td>
</tr>
<tr>
<td>3</td>
<td>2</td>
<td>1</td>
<td>3</td>
</tr>
<tr>
<td>4</td>
<td>3</td>
<td>2</td>
<td>5</td>
</tr>
</tbody>
</table>

**Fig. 2.9.2(a) : Spares Matrix**

**Fig. 2.9.2(b) : Transpose Matrix**
### Transpose Of Sparse Matrix

#### Step 1: copy elements of column 0 of sp1 to sp2.

<table>
<thead>
<tr>
<th>Row</th>
<th>Column</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>4</td>
<td>4</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>5</td>
</tr>
<tr>
<td>1</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>2</td>
<td>3</td>
<td>2</td>
</tr>
</tbody>
</table>

Element of column 0

<table>
<thead>
<tr>
<th>Row</th>
<th>Column</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>3</td>
<td>4</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>5</td>
</tr>
</tbody>
</table>

#### Step 2: copy elements of column 1 of sp1 to sp2.

<table>
<thead>
<tr>
<th>Row</th>
<th>Column</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>4</td>
<td>4</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>5</td>
</tr>
<tr>
<td>1</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>2</td>
<td>3</td>
<td>2</td>
</tr>
</tbody>
</table>

Element of column 0

<table>
<thead>
<tr>
<th>Row</th>
<th>Column</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>3</td>
<td>4</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>5</td>
</tr>
</tbody>
</table>

#### Step 3: copy elements of column 2 of sp1 to sp2.

<table>
<thead>
<tr>
<th>Row</th>
<th>Column</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>4</td>
<td>4</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>5</td>
</tr>
<tr>
<td>1</td>
<td>2</td>
<td>1</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>3</td>
</tr>
<tr>
<td>2</td>
<td>3</td>
<td>2</td>
</tr>
</tbody>
</table>

Element of column 0
Time complexity of manual technique is $O(mn)$. 

\[
\begin{array}{c@{}c@{}c@{}c}
1 & 2 & 3 & 4 \\
5 & 6 & 7 & 8 \\
9 & 10 & 11 & 12 \\
\end{array} \quad \begin{array}{c@{}c@{}c}
1 & 5 & 9 \\
2 & 6 & 10 \\
3 & 7 & 11 \\
4 & 8 & 12 \\
\end{array}
\]
Sparse matrix transpose

Let $B=\begin{pmatrix}
6 & 7 & 5 \\
1 & 2 & 7 \\
2 & 4 & 2 \\
3 & 6 & 5 \\
5 & 0 & 4 \\
5 & 3 & 9 \\
6 & 1 & 8 \\
\end{pmatrix}$

$B^T=\begin{pmatrix}
7 & 6 & 5 \\
2 & 1 & 7 \\
4 & 2 & 2 \\
6 & 3 & 5 \\
0 & 5 & 4 \\
3 & 5 & 9 \\
1 & 6 & 8 \\
\end{pmatrix}$
Simple Sparse matrix transpose

- Time complexity will be $O(n \cdot T)$
  
  $= O(n \cdot mn)$

  $= O(mn^2)$

which is worst than the conventional transpose with time complexity $O(mn)$
Fast Sparse matrix transpose

- In worst case, i.e. $T = m \times n$ (non-zero elements) the magnitude becomes $O(n + mn) = O(mn)$ which is the same as 2-D transpose
- However the constant factor associated with fast transpose is quite high
- When $T$ is sufficiently small, compared to its maximum of $m \cdot n$, fast transpose will work faster
String Manipulation Using Array

- It is usually formed from the character set of the programming language
- The value $n$ is the length of the character string $S$ where $n \geq 0$
- If $n = 0$ then $S$ is called a null string or empty string
Basically a string is stored as a sequence of characters in one-dimensional character array say A.

\[
\text{char A[10] = "STRING" ;}
\]

Each string is terminated by a special character that is null character ‘\0’.

This null character indicates the end or termination of each string.
There are various operations that can be performed on the string:

- To find the length of a string
- To concatenate two strings
- To copy a string
- To reverse a string
- String compare
- Palindrome check
- To recognize a sub string
Write a program to reverse string.

```c++
#include<iostream>
#include<string.h>
using namespace std;

int main ()
{
    char str[50], temp;
    int i, j;

    cout << "Enter a string : ";
    Cin>>str;
    j = strlen(str) - 1;
    for (i = 0; i < j; i++, j--)
    {
        temp = str[i];
        str[i] = str[j];
        str[j] = temp;
    }
    cout << "\nReverse string : " << str;
    return 0;
}
```
/* C++ Program - Concatenate String using inbuilt function */
#include<iostream.h>
#include<string.h>

void main()
{
    clrscr();

    char str1[50], str2[50];

    cout<<"Enter first string : ";
    Cin>>str1;
    cin>>str2;

    strcat(str1, str2);

    cout<<"String after concatenation is "<<str1;
    getch();
}
/* C++ Program - Concatenate String without using inbuilt function */

#include <iostream>
using namespace std;
int main()
{
    char str1[100] = "Hi...";
    char str2[100] = "How are you";
    int i,j;
    cout<<"String 1: "<<str1<<endl;
    cout<<"String 2: "<<str2<<endl;
    for(i = 0; str1[i] != \0; ++i);
    j=0;
    while(str2[j] != \0)
    {
        str1[i] = str2[j];
        i++;  j++;            
    }
    str1[i] = \0;
    cout<<"String after concatenation: "<<str1;
    return 0;
}
To get the length of a C-string string, strlen() function is used.

```cpp
#include <iostream>
#include <cstring>
using namespace std;

int main()
{
    char str[] = "C++ Programming is awesome";
    // you can also use str.length()
    cout << "String Length = " << strlen(str);
    return 0;
}
```

Find length of string without using strlen function

```cpp
#include<iostream>
using namespace std;

int main()
{
    char str[] = "Apple";
    int count = 0;
    while (str[count] != '\0')
        count++;
    cout << "The string is " << str << endl;
    cout << "The length of the string is " << count << endl;
    return 0;
}
```
/* C++ Program - Compare Two String */
#include<iostream.h>
#include<string.h>

void main()
{
    clrscr();
    char str1[100], str2[100];
    cout<<"Enter first string : ";
    gets(str1);
    cout<<"Enter second string : ";
    gets(str2);
    if(strcmp(str1, str2)==0)
    {
        cout<<"Both the strings are equal";
    }
    else
    {
        cout<<"Both the strings are not equal";
    }
    getch();
}
#include <iostream>
#include <string.h>

using namespace std;

int main()
{
    char str1[20], str2[20];
    int i, j, len = 0, flag = 0;

    cout << "Enter the string : ";
    gets(str1);

    len = strlen(str1) - 1;

    for (i = len, j = 0; i >= 0; i--, j++)
        str2[j] = str1[i];

    if (strcmp(str1, str2))
        flag = 1;

    if (flag == 1)
        cout << str1 << " is not a palindrome";
    else
        cout << str1 << " is a palindrome";

    return 0;
}
#include <iostream>
using namespace std;

int main()
{
    int a[10][10], trans[10][10], r, c, i, j;
    cout << "Enter rows and columns of matrix: ";
    cin >> r >> c; // Storing element of matrix
    cout << endl << "Enter elements of matrix: " << endl;
    for(i = 0; i < r; ++i)
        for(j = 0; j < c; ++j)
        {
            cout << "Enter elements a" << i + 1 << j + 1 << " :
            cin >> a[i][j];
        }
    cout << endl << "Entered Matrix: " << endl;
    for(i = 0; i < r; ++i)
        for(j = 0; j < c; ++j)
        {
            cout << " " << a[i][j];
            if(j == c - 1)
                cout << endl << endl;
        }
    // Finding transpose of matrix a[][] and storing it
    for(i = 0; i < r; ++i)
        for(j = 0; j < c; ++j)
        {
            trans[j][i]=a[i][j];
        }
    // Displaying the transpose
    cout << endl << "Transpose of Matrix: " << endl;
    for(i = 0; i < c; ++i)
        for(j = 0; j < r; ++j)
        {
            cout << " " << trans[i][j];
            if(j == r - 1)
                cout << endl << endl;
        }
    return 0;   }
MULTIPLICATION OF TWO POLYNOMIAL

#include<math.h>
#include<stdio.h>
#include<conio.h>
define MAX 17
void init(int p[]);
void read(int p[]);
void print(int p[]);
void add(int p1[],int p2[],int p3[]);
void multiply(int p1[],int p2[],int p3[]);

/*Polynomial is stored in an array, p[i] gives coefficient of x^i.
 a polynomial 3x^2 + 12x^4 will be represented as
 (0,0,3,0,12,0,0,....)
 */

void main()
{
 int p1[MAX],p2[MAX],p3[MAX];
 int option;
do
 {
 printf("nn1 : create 1’st polynomial");
 printf("n2 : create 2’nd polynomial");
 printf("n3 : Add polynomials");
 printf("n4 : Multiply polynomials");
 printf("n5 : Quit");
 printf("nEnter your choice :");
 scanf("%d",&option);

 switch(option)
 {
 case 1:read(p1);break;
 case 2:read(p2);break;
 case 3:add(p1,p2,p3);
 printf("n1’st polynomial - > ");
 print(p1);
 printf("n2’nd polynomial - > ");
 print(p2);
 printf("n Sum = ");
 print(p3);
 break;
 case 4:multiply(p1,p2,p3);
 printf("n1’st polynomial - > ");
 print(p1);
 printf("n2’nd polynomial - > ");
 print(p2);
 printf("n Product = ");
 print(p3);
 break;
 }
}while(option!=5);
MULTIPLICATION OF TWO POLYNOMIAL

```c
void read(int p[]) {
    int n, i, power, coeff;
    init(p);
    printf("n Enter number of terms :");
    scanf("%d", &n);
    /* read n terms */
    for (i=0; i<n; i++) {
        printf("n enter a term(power coeff.)");
        scanf("%d%d", &power, &coeff);
        p[power]=coeff;
    }
}

void print(int p[]) {
    int i;
    for (i=0; i<MAX; i++)
        if (p[i]!=0)
            printf("%dX^%d
", p[i], i);
}

void add(int p1[], int p2[], int p3[]) {
    int i;
    for (i=0; i<MAX; i++)
        p3[i]=p1[i]+p2[i];
}

void multiply(int p1[], int p2[], int p3[]) {
    int i, j;
    init(p3);
    for (i=0; i<MAX; i++)
        for (j=0; j<MAX; j++)
            p3[i+j]=p3[i+j]+p1[i]*p2[j];
}

void init(int p[]) {
    int i;
    for (i=0; i<MAX; i++)
        p[i]=0;
}

********END********
```
#include <iostream>

using namespace std;

int main()
{
    int a[10][10], trans[10][10], r, c, i, j;

    cout << "Enter rows and columns of matrix: ";
    cin >> r >> c;

    // Storing element of matrix enter by user in array a[][].
    cout << endl << "Enter elements of matrix: " << endl;
    for(i = 0; i < r; ++i)
    for(j = 0; j < c; ++j)
    {
        cout << "Enter elements a" << i + 1 << j + 1 << ":
        ";
        cin >> a[i][j];
    }

    // Displaying the matrix a[][]
    cout << endl << "Entered Matrix: " << endl;
    for(i = 0; i < r; ++i)
    for(j = 0; j < c; ++j)
    {
        cout << " ";
        if(j == c - 1)
            cout << endl << endl;
    }

    // Finding transpose of matrix a[][] and storing it in array trans[][].
    for(i = 0; i < r; ++i)
    for(j = 0; j < c; ++j)
    {
        trans[j][i]=a[i][j];
    }
}

// PROF. ANAND GHARU
FIND SIMPLE TRANSPOSE OF MATRIX

// Displaying the transpose, i.e., Displaying array trans[].

cout << endl << "Transposes of Matrix: " << endl;

for(i = 0; i < c; ++i)
    for(j = 0; j < r; ++j)
        {
            cout << " " << trans[i][j];
            if(j == r - 1)
                cout << endl << endl;
        }

return 0;
THANK YOU !!!!!

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